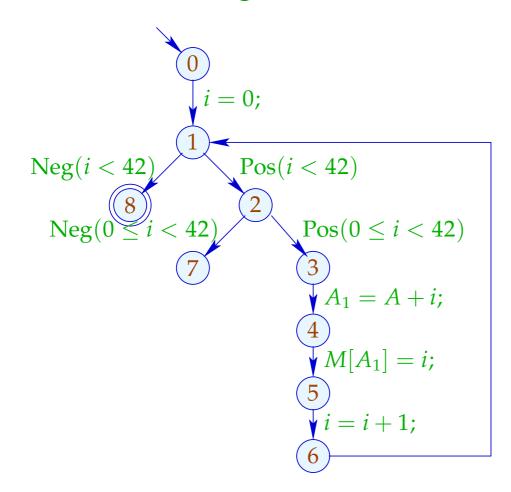
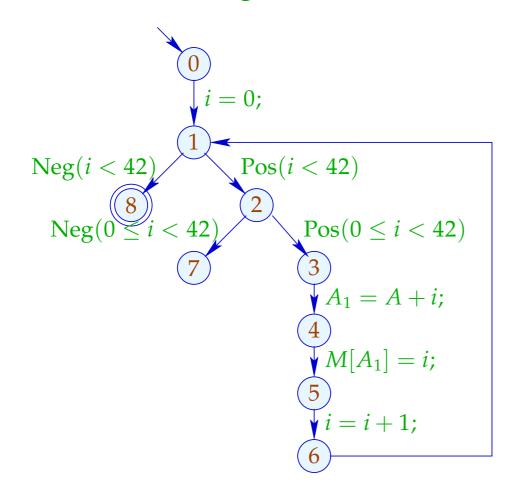
#### Narrowing Iteration in the Example:



	0		1	
	1	и	1	и
0	$-\infty$	$+\infty$	$-\infty$	$+\infty$
1	0	$+\infty$	0	$+\infty$
2	0	$+\infty$	0	41
3	0	$+\infty$	0	41
4	0	$+\infty$	0	41
5	0	$+\infty$	0	41
6	1	$+\infty$	1	42
7	42	$+\infty$		
8	42	$+\infty$	42	$+\infty$

#### Narrowing Iteration in the Example:



	0		1		2	
	1	и	1	и	1	и
0	$-\infty$	$+\infty$	$-\infty$	$+\infty$	$-\infty$	$+\infty$
1	0	$+\infty$	0	$+\infty$	0	42
2	0	$+\infty$	0	41	0	41
3	0	$+\infty$	0	41	0	41
4	0	$+\infty$	0	41	0	41
5	0	$+\infty$	0	41	0	41
6	1	$+\infty$	1	42	1	42
7	42	$+\infty$	⊥			
8	42	$+\infty$	42	$+\infty$	42	42

#### Discussion:

- $\rightarrow$  We start with a safe approximation.
- $\rightarrow$  We find that the inner check is redundant :-)
- $\rightarrow$  We find that at exit from the loop, always i = 42 :-))
- → It was not necessary to construct an optimal loop separator :-)))

### Last Question:

Do we have to accept that narrowing may not terminate ???

#### 4. Idea: Accelerated Narrowing

Assume that we have a solution  $\underline{x} = (x_1, \dots, x_n)$  of the system of constraints:

$$x_i \supseteq f_i(x_1,\ldots,x_n), \quad i=1,\ldots,n \tag{1}$$

Then consider the system of equations:

$$x_i = x_i \sqcap f_i(x_1, \ldots, x_n), \quad i = 1, \ldots, n$$
(4)

Obviously, we have for monotonic  $f_i: H^k \underline{x} = F^k \underline{x}$ :-) where  $H(x_1, \dots, x_n) = (y_1, \dots, y_n)$ ,  $y_i = x_i \sqcap f_i(x_1, \dots, x_n)$ .

In (4), we replace  $\square$  durch by the novel operator  $\square$  where:

$$a_1 \sqcap a_2 \sqsubseteq a_1 \sqcap a_2 \sqsubseteq a_1$$

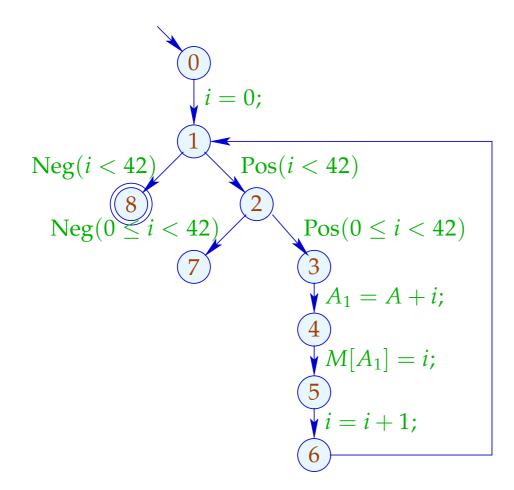
#### ... for Interval Analysis:

We preserve finite interval bounds :-)

Therefore,  $\perp \sqcap D = D \sqcap \perp = \perp$  and for  $D_1 \neq \perp \neq D_2$ :  $(D_1 \sqcap D_2) x = (D_1 x) \sqcap (D_2 x)$  where  $[l_1, u_1] \sqcap [l_2, u_2] = [l, u]$  mit  $l = \begin{cases} l_2 & \text{if } l_1 = -\infty \\ l_1 & \text{otherwise} \end{cases}$  $u = \begin{cases} u_2 & \text{if } u_1 = \infty \\ u_1 & \text{otherwise} \end{cases}$ 

□ is not commutative !!!

#### Accelerated Narrowing in the Example:



	0		1		2	
	1	и	1	и	1	и
0	$-\infty$	$+\infty$	$-\infty$	$+\infty$	$-\infty$	$+\infty$
1	0	$+\infty$	0	$+\infty$	0	42
2	0	$+\infty$	0	41	0	41
3	0	$+\infty$	0	41	0	41
4	0	$+\infty$	0	41	0	41
5	0	$+\infty$	0	41	0	41
6	1	$+\infty$	1	42	1	42
7	42	$+\infty$	-	L		L
8	42	$+\infty$	42	$+\infty$	42	42

#### Discussion:

- $\rightarrow$  Warning: Widening also returns for non-monotonic  $f_i$  a solution. Narrowing is only applicable to monotonic  $f_i$  !!
- → In the example, accelerated narrowing already returns the optimal result :-)
- → If the operator □ only allows for finitely many improvements of values, we may execute narrowing until stabilization.
- $\rightarrow$  In case of interval analysis these are at most:

 $#points \cdot (1 + 2 \cdot #Vars)$ 

#### **1.6 Pointer Analysis**

# Questions:

- $\rightarrow$  Are two addresses possibly equal?
- $\rightarrow$  Are two addresses definitively equal?

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May Alias Must Alias



The analyses so far without alias information:

- (1) Available Expressions:
- Extend the set Expr of expressions by occurring loads M[e].
- Extend the Effects of Edges:

$$[x = e;]]^{\sharp} A = (A \cup \{e\}) \setminus Expr_{x}$$
  
$$[x = M[e];]]^{\sharp} A = (A \cup \{e, M[e]\}) \setminus Expr_{x}$$
  
$$[M[e_{1}] = e_{2};]]^{\sharp} A = (A \cup \{e_{1}, e_{2}\}) \setminus Loads$$

- (2) Values of Variables:
- Extend the set *Expr* of expressions by occurring loads M[e].
- Extend the Effects of Edges:

$$\llbracket x = M[e]; \rrbracket^{\sharp} V e' = \begin{cases} \{x\} & \text{if } e' = M[e] \\ \emptyset & \text{if } e' = e \\ V e' \setminus \{x\} & \text{otherwise} \end{cases}$$
$$\llbracket M[e_1] = e_2; \rrbracket^{\sharp} V e' = \begin{cases} \emptyset & \text{if } e' \in \{e_1, e_2\} \\ V e' & \text{otherwise} \end{cases}$$

- (3) Constant Propagation:
- Extend the abstract state by an abstract store *M*
- Execute accesses to known memory locations!

$$\begin{bmatrix} x = M[e]; \end{bmatrix}^{\sharp} (D, M) = \begin{cases} (D \oplus \{x \mapsto Ma\}, M) & \text{if} \\ & [e]]^{\sharp} D = a \sqsubset \top \\ (D \oplus \{x \mapsto \top\}, M) & \text{otherwise} \end{cases}$$
$$\begin{bmatrix} M[e_1] = e_2; \end{bmatrix}^{\sharp} (D, M) = \begin{cases} (D, M \oplus \{a \mapsto [e_2]]^{\sharp} D\}) & \text{if} \\ & [e_1]]^{\sharp} D = a \sqsubset \top \\ (D, \underline{\top}) & \text{otherwise} \end{cases} \text{ where}$$
$$\underline{\top} a = \top \qquad (a \in \mathbb{N})$$

#### Problems:

- Addresses are from ℕ :-(
   There are no infinite strictly ascending chains, but ...
- Exact addresses at compile-time are rarely known :-(
- At the same program point, typically different addresses are accessed ...
- Storing at an unknown address destroys all information M
   :-(
- $\implies$  constant propagation fails :-(
- $\implies$  memory accesses/pointers kill precision :-(

#### Simplification:

- We consider pointers to the beginning of blocks A which allow indexed accesses A[i] :-)
- We ignore well-typedness of the blocks.
- New statements:

x = new();//allocation of a new blockx = y[e];//indexed read access to a block $y[e_1] = e_2;$ //indexed write access to a block

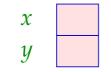
- Blocks are possibly infinite :-)
- For simplicity, all pointers point to the beginning of a block.

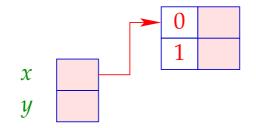
Simple Example:

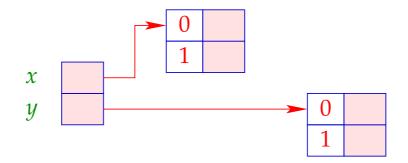
$$x = new();$$
  
 $y = new();$   
 $x[0] = y;$   
 $y[1] = 7;$ 

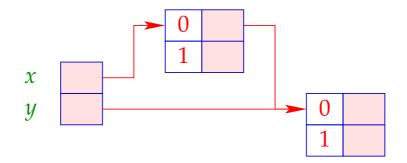
0  

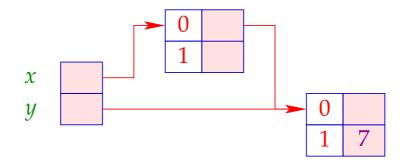
$$x = new();$$
  
1  
 $y = new();$   
2  
 $x[0] = y;$   
3  
 $y[1] = 7;$   
4

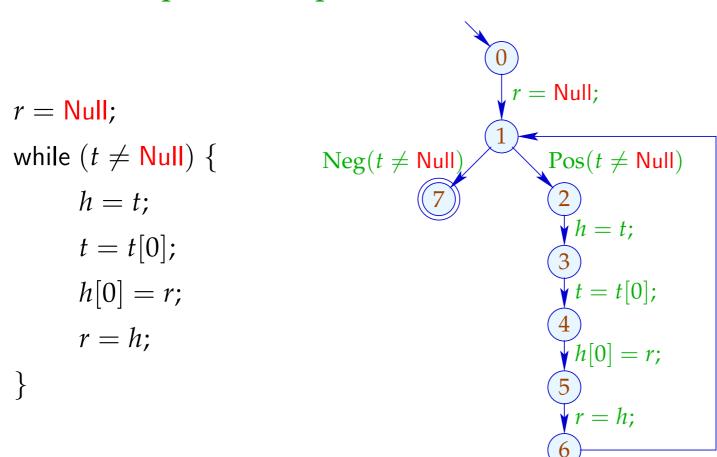












More Complex Example:

#### **Concrete Semantics:**

A store consists of a finite collection of blocks.

After *h* **new-**operations we obtain:

$$Addr_h = \{ref a \mid 0 \le a < h\}$$
// addresses $Val_h = Addr_h \cup \mathbb{Z}$ // values $Store_h = (Addr_h \times \mathbb{N}_0) \rightarrow Val_h$ // store $State_h = (Vars \rightarrow Val_h) \times Store_h$ // states

For simplicity, we set: 0 = Null

Let  $(\rho, \mu) \in State_h$ . Then we obtain for the new edges:

$$\begin{bmatrix} x = \mathsf{new}(); \end{bmatrix} (\rho, \mu) = (\rho \oplus \{x \mapsto \mathsf{ref} h\}, \\ \mu \oplus \{(\mathsf{ref} h, i) \mapsto \mathbf{0}, (i \in \mathbb{N}_0) \\ \begin{bmatrix} x = y[e]; \end{bmatrix} (\rho, \mu) = (\rho \oplus \{x \mapsto \mu (\rho y, \llbracket e \rrbracket \rho)\}, \mu) \\ \llbracket y[e_1] = e_2; \rrbracket (\rho, \mu) = (\rho, \mu \oplus \{(\rho y, \llbracket e_1 \rrbracket \rho) \mapsto \rho \llbracket e_2 \rrbracket \rho\}) \end{bmatrix}$$

#### Warning:

This semantics is **too** detailled in that it computes with absolute Addresses. Accordingly, the two programs:

$$x = new();$$
  $y = new();$   
 $y = new();$   $x = new();$ 

are not considered as equivalent !!?

### Possible Solution:

Define equivalence only up to permutation of addresses :-)

#### Alias Analysis 1. Idea:

- Distinguish finitely many classes of blocks.
- Collect all addresses of a block into one set!
- Use sets of addresses as abstract values!

 $\implies$  Points-to-Analysis

# ... in the Simple Example:

0  

$$x = new();$$
  
1  
 $y = new();$   
2  
 $x[0] = y;$   
3  
 $y[1] = 7;$   
4

	x	y	(0,1)
0	Ø	Ø	Ø
1	$\{(0,1)\}$	Ø	Ø
2	$\{(0,1)\}$	$\{(1, 2)\}$	Ø
3	$\{(0,1)\}$	$\{(1, 2)\}$	$\{(1,2)\}$
4	$\{(0,1)\}$	$\{(1, 2)\}$	$\{(1,2)\}$